

Survey/review study

Network Learning for Biomarker Discovery

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Abstract: Everything is connected and thus networks are instrumental in not only modeling complex systems with many components, but also accommodating knowledge about their components. Broadly speaking, network learning is an emerging area of machine learning to discover knowledge within networks. Although networks have permeated all subjects of sciences, in this study we mainly focus on network learning for biomarker discovery. We first overview methods for traditional network learning which learn knowledge from networks with centrality analysis. Then, we summarize the network deep learning, which are powerful machine learning models that integrate networks (graphs) with deep neural networks. Biomarkers can be placed in proper biological networks as vertices or edges and network learning applications for biomarker discovery are discussed. We finally point out some promising directions for future work about network learning.

Keywords: network learning; graph; centrality; graph convolutional network; biomarker discovery

1. Introduction

Terminology *network learning* in this study means an emerging area of machine learning to discover knowledge hidden within networks. Note that by a Google search, one can find a popular terminology *networked learning*, which is an online learning method that connects individuals or groups with internet technologies and transfers information between educator(s) and learner(s) via internet. Such *networked learning* is not the topic of this study. Network learning is emerging, yet has rooted in a quite old mathematical branch-graph theory. Terminologies *network* and *graph* thus have the same meaning and are used interchangeably in the contemporary literature. The graph theory has been applied to practical problems since its inception in 1736, when Swiss mathematician Leonhard Euler used it to solve the real-world problem of how best it is to circumnavigate the seven bridges of Königsberg [1]. Since then, graphs have developed into powerful tools for engineered networks, neural networks, information networks, biological networks, semantic networks, economic networks, social networks, and ecological networks, just to name a few. An essential factor of this growth is that graphs (networks) can not only model complex systems with many components, but also contain rich knowledge about their components as parts of a whole. In addition, networks are also effective instrumental to model unstructured data [2] and to integrate multi-view data [3–5].

A generic (dynamic) network can be represented by a quadruple as follows [6]:

$$G(t) = \{V(t), E(t); A(t), D(t)\} \quad (1)$$

where t represents either simulated or real time; V represents the set of all vertices, also known as nodes; E represents the set of all edges, also known as links, arcs; A represents an $n \times n$ matrix that defines the structure, yielding topology, and is also called a weight matrix, where n is the number of vertices; D represents a set of equations describing dynamics of vertices and/or edges with time. In this study, we mainly focus on static network learning, i.e. learning based on $G = (V, E; A)$, where vertices, edges, and weights don't evolve with time.

In $G = (V, E; A)$, the length of a path is the sum of the weights of the edges on the path. A path from vertex u to vertex v is the shortest path if its length is the smallest possible among all paths from vertex u to vertex v . The length of the shortest path from vertex u to vertex v is also called the distance between vertices u and v , and is denoted by $d(u, v)$. Furthermore, $G = (V, E; A)$ is called an undirected network if $A^T = A$ and otherwise a directed network.

When $a_{ij} = 1$, it indicates that there is an edge between vertices v_i and v_j ; otherwise, $a_{ij} = 0$ and A becomes a binary matrix, which is also called the adjacent matrix of the network. In this case, a static network can be denoted by $G = (V, E)$. Vertices and edges together are called elements of networks.

A biomarker, or biological marker, is a measurable indicator of some biological states or conditions. According to their functions, biomarkers can be classified as disease-related biomarkers and drug-related biomarkers. Disease-related biomarkers can be further divided into three categories: diagnostic biomarkers, predictive biomarkers and prognostic biomarkers. Diagnostic biomarkers give an indication of the existence of a disease. Predictive biomarkers are indicators of probable effect of treatment on patients, which can help assess the most likely response to a particular treatment type. Prognostic biomarkers show how a disease may develop in an individual case regardless of the type of treatment [7]. Drug-related biomarkers indicate whether a drug is effective in a specific patient and how the patient's body responds to it. According to their properties, biomarkers can be classified as molecular biomarkers, tissue biomarkers and digital (imaging) biomarkers.

Although a huge amount of biomedical data has been stored in various databases in different types such as the sequence, expression, association, compared to the complexity of the diseases, the available biomedical data is still insufficient for the accurate prediction of biomarkers. Typically complex diseases are caused by multiple biomarkers [8], and there is synthetic lethality between genes [9]. In addition, the best way to understand an individual (e.g., biomarkers, drugs, diseases) or a relationship (interactions, associations) between two individuals is placing the individual into suitable networks. Therefore, biological networks play an important role in biomarker discovery. With the development of advanced technologies, various types of biomolecular networks can be constructed, e.g. human disease networks [10, 11], disease gene networks [12], drug-target networks [13], brain networks [14], protein-protein interaction (PPI) networks [15, 16], drug-drug interaction (DDI) networks [17] and other biological networks [18, 19], just to name a few. There are also many ad hoc networks constructed with multi-omics data, such as co-expression networks and similarity networks, in the literature of computational medicine. Rich knowledge contained in these networks can help understand drugs, diseases, and drug targets and ultimately benefit drug design and disease treatment [20, 21].

Besides genes and proteins, various studies have confirmed that microRNAs (miRNAs), long non-coding RNAs (lncRNAs), circular RNAs (circRNAs), and Piwi-interacting RNAs play important roles in the occurrence and development of diseases. Therefore, the identification of these RNA biomarkers could help understand the pathogenesis of complex diseases. However, biological experimental verification methods are costly and time-consuming, and thus computational model-based RNA and disease data analysis methods are promising alternatives for the RNA biomarker identification. Medical images play an extremely important role in the clinical diagnosis, prognosis, and treatment of diseases, especially, brain disorders. In this study, we mainly focus on molecular biomarkers (including genes, proteins, and various RNAs) and imaging biomarkers, which are either disease-related or drug-related.

In past decades, many network learning methods have been developed to mine knowledge about biomarkers in biological network data. This study is to give a systematic review of network learning and applications for biomarker discovery as shown in Figure 1. The rest of this paper is organized as follows: We first overview methods for traditional network learning, which learn knowledge about biomarkers from networks with centrality analysis and their applications for biomarker discovery in Section 2. Then, we discuss the network deep learning methods (graph convolution network learning), which integrate networks (graphs) with deep neural networks, and their applications for biomarker discovery in Section 3. Other network learning methods, which include network-energy-based methods and nonnegative matrix factorization (NMF), along with their applications for biomarker discovery are discussed in Section 4. Finally, in Section 5 we point out some promising directions of future work along network learning.

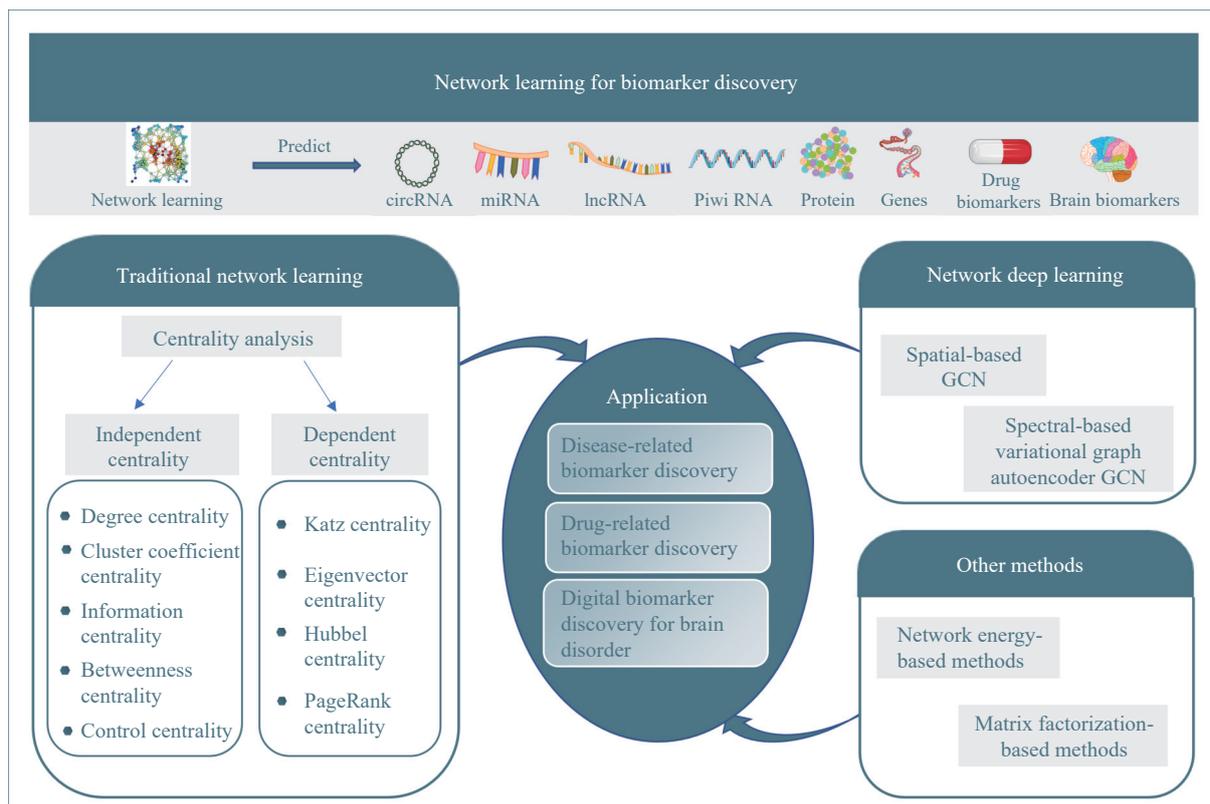


Figure 1. The overview of this study.

2. Traditional Network Learning

In this section, we overview traditional network learning methods with a focus on the centrality-based methods for learning the importance or the specialty of the network elements, as well as their applications in computational medicine for biomarker discovery.

2.1. Centrality Analysis

Centrality indices are to quantify an intuitive feeling that some network elements are more important than others in networks. We classify centrality indices in the literature [22, 23] into two categories: independent centrality and dependent centrality. The independent centrality of a network element is independent of the centrality of other network elements in the network while the dependent centrality of a network element depends on the centrality of all network elements in the network.

2.1.1. Independent Centrality

Although many different centrality indices have been proposed in the literature [22, 23], some of them have certain overlaps for learning knowledge. In the following, we first introduce some widely used independent centrality indices with the least overlap, including degree centrality, cluster coefficient centrality, information centrality, betweenness centrality, and control centrality.

(1) Degree Centrality and Strength

The simplest centrality is the degree centrality $c_D(i) = d_i$ of a vertex v_i in an undirected graph $G = (V, E)$ where d_i is the number of edges in E that has vertex v_i as an endvertex. In a directed network $G = (V, E)$, two variants of the degree centrality may be appropriate: the in-degree centrality $c_{iD}(i) = d^-(i)$ and the out-degree centrality $c_{oD}(i) = d^+(i)$, where $d^-(i)$ is the number of edges in E with the destination of vertex v_i while $d^+(i)$ is the number of edges in E that has the origin of vertex v_i . In a weighted undirected network $G = (V, E; A)$, the weighted degree centrality of a vertex v_i , which is the sum of weights of edges in E that has the vertex v_i as an endvertex, is called the strength in literature.

(2) Cluster Coefficient Centrality

The clustering coefficient of a vertex v_i in a network quantifies how close its neighbors are to being a clique (complete graph), and can be defined as

$$c_{CC}(i) = \frac{2| \{ (v_j, v_k) \in E | v_j, v_k \in \mathcal{N}(v_i) \} |}{k_i(k_i - 1)} \quad (2)$$

where $\mathcal{N}(v_i)$ is the neighborhood of vertex v_i , i.e., $\mathcal{N}(v_i) = \{v_j | (v_j, v_i) \in E\}$ and $k_i = |\mathcal{N}(v_i)|$ is the number of vertices in $\mathcal{N}(v_i)$.

(3) Closeness Centrality and Information Centrality

The closeness centrality of vertex v_i is defined as the reciprocal of the total distance between vertex v_i and any other vertex v_j as follows

$$c_{Cl}(i) = \frac{n}{\sum_{v_j \in V} d(v_i, v_j)} \tag{3}$$

When an undirected network is disconnected, the closeness centrality is useless as its value for all vertices will be zero. To mitigate this drawback, the information centrality has been designed.

The information I_{ij} that can be transmitted between two vertices v_i and v_j is defined as the reciprocal of the topological distance $d(i, j)$, i.e., $I_{ij} = 1/d(v_i, v_j)$. The information centrality of the vertex v_i is defined as the harmonic average information I_{ij} over a network as follows:

$$c_I(i) = \left[\frac{1}{n} \sum_{j \neq i} \frac{1}{I_{ij}} \right]^{-1} \tag{4}$$

which is to measure information that can be transmitted between vertex v_i and any other vertex in a network. It can be seen that when an undirected network is connected, the closeness centrality of its element is exactly the same as its information centrality. However, when an undirected network is disconnected, the information centrality still makes sense while the closeness centrality does not.

(4) Betweenness Centrality

The betweenness centrality of vertex v_i can be defined as follows:

$$c_B(i) = \sum_{\substack{s \in V \\ s \neq i}} \sum_{\substack{t \in V \\ t \neq i}} \delta_{st}(i), \quad \delta_{st}(i) = \frac{\sigma_{st}(i)}{\sigma_{st}} \tag{5}$$

where $\sigma_{st}(i)$ denotes the number of all shortest paths between vertices s and t that contain vertex v_i while σ_{st} denotes the number of all shortest paths between vertices s and t , and thus $\delta_{st}(i)$ is the fraction of shortest paths between vertices s and t that contain vertex v_i . Similarly, the betweenness centrality of edge e can be defined as follows:

$$c_B(e) = \sum_{\substack{s \in V \\ s \neq u}} \sum_{\substack{t \in V \\ t \neq u}} \delta_{st}(e), \quad \delta_{st}(e) = \frac{\sigma_{st}(e)}{\sigma_{st}} \tag{6}$$

where $\sigma_{st}(e)$ denotes the number of all shortest paths between vertices s and t that contain edge e while σ_{st} denotes the number of all shortest paths between vertices s and t , and thus $\delta_{st}(e)$ is the fraction of shortest paths between vertices s and t that contain edge e .

(5) Control Centrality

Letting A be the $n \times n$ adjacent matrix of a network, the control centrality of vertex v_i can be defined as follows [24,25]:

$$c_{Co} = \text{rank}(C^{(i)}), \quad C^{(i)} = [e_i, Ae_i, \dots, A^{n-1}e_i] \tag{7}$$

where e_i is the i -th column of the $n \times n$ identity matrix. The control centrality measures the controllability [26] of a node on which a control signal is actuated.

A vertex is called a hub if its centrality value in a network is relatively higher than a user-specified threshold. For different centralities, different sets of hubs may be produced from the same network. For a network $G = (V, E)$ and any centrality c , we can define the global centrality of G as follows:

$$c(G) = \frac{1}{n} \sum_{u \in V} c(u) \tag{8}$$

2.1.2. Dependent Centrality

The independent centralities of one vertex are independent of other vertices. Actually, it is reasonable that the more central a vertex is, the more central its neighbors are and vice versa. This kind of measure is called the dependent centrality. In the following, centrality values are denoted as vectors, each of whose component is corresponding to the centrality of one vertex in the network. All dependent centralities are typically calculated by solving linear systems.

(1) Katz Centrality

The Katz centrality is to measure the impact of a vertex v_i on any vertex v_j of a network. Intuitively, vertex v_i can impact on any vertex v_j if there is a path from vertex v_i to vertex v_j . In addition, the longer the path between two vertices v_i and v_j is, the smaller the impact of vertex v_i on v_j should be. To take the effect of path length into consideration, a damping factor $0 < \alpha < 1$ is introduced. As a result, the Katz centrality (c_K) can be mathematically defined as follows:

$$c_k(i) = \sum_{k=0}^{\infty} \sum_{j=1}^n \alpha^k (A^k)_{ji} \tag{9}$$

where A is the adjacency matrix of the network. Note that $(A^k)_{ji}$ is the number of paths from vertex v_i to vertex v_j with the length of k . In the matrix-vector format, we have

$$c_k = \sum_{k=0}^{\infty} \alpha^k (A^T)^k \mathbf{1}_n \tag{10}$$

where $\mathbf{1}^n$ is the n -dimensional vector where every entry is 1. Let λ_1 be the largest eigenvalue of matrix A , which is a positive number, and let $\alpha < 1/\lambda_1 < 1$. Then, we have

$$c_k = \sum_{k=0}^{\infty} \alpha^k (A^T)^k \mathbf{1}_n = (I - \alpha A^T)^{-1} \mathbf{1}_n \text{ or } (I - \alpha A^T) c_K = \mathbf{1}_n \tag{11}$$

(2) Eigenvector Centrality

Eigenvector centrality assumes that the centrality value $c_{Ei}(i)$ of vertex v_i depends on the values of each adjacent vertex, specifically it is proportional to the sum of the values of each adjacent vertex. Therefore, in the matrix-vector format we have the following equation:

$$c_{Ei} = \alpha A c_{Ei} \text{ or } A c_{Ei} = \lambda c_{Ei} \tag{12}$$

where $\lambda = 1/\alpha$. It can be proved that if a network is undirected and connected, then the largest eigenvalue λ_1 of A is simple and all entries of the eigenvector corresponding to λ_1 are of the same sign. Therefore, the eigenvector centrality is computed as the scaled eigenvector corresponding to λ_1 .

(3) Hubbel Centrality

Further to the eigenvector centrality, Hubbel also took some prior preference information about the centrality value (represented by a column vector E) into account. As a result, the Hubbel centrality c_{Hu} satisfies the following equation

$$c_{Hu} = E + \alpha A c_{Hu} \tag{13}$$

If there is no specific prior preference information, E can be taken as $\mathbf{1}_n$. Then, we have

$$c_{Hu} = \mathbf{1}_n + \alpha A c_{Hu} \text{ or } (I - \alpha A) c_{Hu} = \mathbf{1}_n \tag{14}$$

which is the same as the Katz centrality for undirected networks.

(4) PageRank Centrality

The initial PageRank centrality c_{PR} can be viewed as the extension of the eigenvalue centrality by taking the degree of neighbor vertices into account as follows:

$$c_{PR}(v) = d \sum_{u \in \Gamma_v^-} \frac{c_{PR}(u)}{d^+(u)} \tag{15}$$

where $c_{PR}(u)$ is the PageRank centrality value of vertex u and d is a proportional constant. $d^+(u)$ is the out degree of vertex u and Γ_v^- is the set of vertices pointing to vertex v . In the matrix-vector format, the initial PAGERANK centrality can be expressed as

$$c_{PR} = d P c_{PR} \tag{16}$$

where the transition matrix $P = (p_{ij})_{n \times n}$ is calculated as follows:

$$p_{ij} = \begin{cases} \frac{1}{d^+(j)}, & \text{if } (v_j, v_i) \in E \\ 0, & \text{others} \end{cases} \tag{17}$$

Therefore, c_{PR} is actually the scaled eigenvector of the transition matrix P . The final PageRank centrality can be

viewed as the type of the Hubbel centrality in that the adjacent matrix is replaced with the transition matrix as follows:

$$c_{PR} = dPc_{PR} + (1 - d)\frac{1_n}{n} \quad (18)$$

The random walk starting with a vertex on a network is actually to calculate the PageRank centrality of that vertex [27, 28]. Especially, random walk-based algorithms, such as node2vec [28], have been widely used for extracting features of vertices in networks. The above presented dependent centralities follow the idea of positive feedback: the centrality of a vertex is higher if it is connected to other high-valued vertices. In addition, the eigenvector centrality is the fundamental dependent centrality as other dependent centrality can be viewed as its generalization in different ways.

2.2. Applications

2.2.1. Disease-Related Biomarker Discovery

Jeong et al. [29] conclude that the most highly connected proteins in the cell are the most important for its survival. Han et al. [30] define two types of hubs: party hubs and date hubs, based on the degree centrality in PPI networks, and uncover that these hubs play important biological roles. With various other evidence [31, 32] about the relationships between the centrality and biological roles of network elements, many centralities have been applied to learn biological knowledge from biological networks in past decades. Essential proteins are indispensable proteins for supporting cellular life and thus are important biomarkers [9]. The degree centrality, information centrality, betweenness centrality and other dependent centralities have been used to predict essential proteins from PPI networks with great accuracy [33, 34]. The fundamental dependent centrality and eigenvector centrality have been used to predict essential proteins [34–38]. Tang et al. [39] develop a software package to predict essential proteins based on several commonly used centralities, including degree centrality, betweenness centrality, information centrality, and eigenvector centrality, to name a few. Understanding the role of genetics in diseases is one of the most important goals of the biological sciences. However, determining disease-associated genes requires laborious experiments and thus the centrality indices can be used to predict good candidate disease-associated genes before experimental analysis [40]. The random walk can be used to either directly predict disease-related biomarkers [41, 42] or to learn the features of biomarkers for some machine learning-based prediction methods [43, 44]. Recently, Gentili et al. [5] use the random walk to integrate multi-omics data for disease gene prioritization.

2.2.2. Drug-Related Biomarker Discovery

Traditional drug discovery strategies are not only high monetary-demanding, but also time-consuming. Drug repositioning (also called drug repurposing) is now becoming an effective drug discovery strategy, which involves the investigation on existing drugs for treating different diseases [45]. In drug repositioning [46, 47], a key is to select a list of genes called the gene signature to represent a disease. By placing genes in proper networks, a number of centralities have been used to create gene signatures [48, 49] from gene networks. Drug targets, which are important biomarkers, can be interpreted as steering nodes in controlled biomolecular networks while drugs are viewed as the control signals. Wu et al. [50] develop some seminal theories for the controllability of complex biomolecular networks and design several variants of the control centrality, which have been applied to identify drug targets from regulatory biological networks [51–53].

2.2.3. Digital Biomarkers for Brain Disorders

Interconnections of structurally segregated and functionally specialized regions of the human cerebral cortex can be represented by structural brain networks based on structural brain images [54–57]. The analysis of the large-scale structural brain networks has revealed that brain regions within the structural core share with high degree, strength, and betweenness centrality [58]. Both remitted geriatric depression (RGD) and amnesic mild cognitive impairment (aMCI) are associated with a high risk of developing Alzheimer's Disease (AD). The analysis of structural brain networks with several centralities finds some direct evidence for the association of a great majority of convergent connectivity and a minority of divergent connectivity between RGD and aMCI patients, which may lead to increased attention in defining a population at risk of AD [59]. Gu et al. [60] apply the control centrality to structural brain networks to the region of brains with special cognitive functions, which can be potential target regions for treating brain disorders. With the proper parcellation scheme of the human cerebral cortex, functional brain networks can be constructed based on functional brain magnetic resonance imaging (MRI) images. Mostafa et al. [61] and Yin et al. [62] define the features of patients from their functional brain networks by integrating the centralities with other information to develop the methods for diagnosis of autism spectrum disorder.

3. Network Deep Learning

Convolutional neural network (CNN)-based deep learning has been very successful in the computer vision domain and natural language processing domain as the imaging data and text data are well structured and the neighborhood for the convolutional operation is obvious. By utilizing the neighborhood relations of vertices in a network (graph) [63] for the convolutional operation, the numerous types of graph convolutional networks (GCNs) [64, 65] have been proposed, which can be classified as spatial-based GCNs and spectral-based GCNs.

3.1. Spatial-Based GCN

Analogous to the convolutional operation of a conventional CNN on an image, the spatial-based graph convolutions convolve the features of a central vertex with the features of its neighbors to derive the updated features for the central vertex. The spatial graph convolutional operation essentially propagates vertex information along edges across a whole graph. The graph convolution for vertex u at the p th layer is designed as [66]:

$$y^p(u) = x^p(u) + \sum_{v \in \mathcal{N}(u)} x^p(v) \quad (19)$$

$$x^{p+1}(u) = f(y^p(u) \Theta_{|N(u)|}^p) \quad (20)$$

where $x^p(u)$ is the feature vector of vertex u at the p th layer, and $y^p(u)$ is a mediate vector with the same dimension as $x^p(u)$. $\mathcal{N}(u)$ is the set of all neighbor vertices of vertex u , $|N(u)|$ is the number of vertices in $\mathcal{N}(u)$, $f(\cdot)$ is an activation function and $\Theta_{|N(u)|}^p$ is the weight matrix for vertices with the same degree as $|N(u)|$ at the p th layer. However, for large graphs, the number of unique values of vertex degree is often very large. Consequently, there are too many weight matrices to be learned at each layer, possibly leading to the overfitting problem.

In addition, as the number of neighbors of a vertex can vary from one to a thousand or even larger, it is inefficient to take the full size of a vertex's neighborhood. GraphSage [67] adopts sampling to obtain a fixed number of neighbors for each node and replaces Equation (19) by a general aggregate operation, and the graph convolution is performed by

$$y^p(u) = \text{Agg}_p(\{x^p(v), \forall v \in S_{\mathcal{N}(v)}\}) \quad (21)$$

$$x^{p+1}(u) = f(y^p(u) \Theta^p) \quad (22)$$

where Agg_p is an aggregation function at the p th layer, and $S_{\mathcal{N}(v)}$ is a random sample of the node v 's neighbors. The aggregation function should be invariant to the permutations of node orderings such as a mean, sum or max function [64, 68]. Note that in Equation (22) the weight matrix Θ^p does not depend on the vertex degree. As a result, the number of learnable parameters is greatly reduced and the overfitting problem can be mitigated.

3.2. Spectral-Based Variational Graph Autoencoder

The autoencoder (AE) and its variant variational autoencoder (VAE) are effective tools to learn the hidden features from raw data (or features) [69]. Kipf and Welling [70] propose a two-layer variational graph autoencoder (VGAE) that extends VAE to graphs for the first time. Consider an undirected, unweighted graph $G = (V, E)$ with $n = |V|$ vertices nodes. Let A be the adjacency matrix of G and D be its degree matrix. Furthermore, let H be an $n \times f$ matrix consisting of hidden features of all vertices to be learned and X be an $n \times d$ matrix consisting of raw features of all vertices. VGAE includes two parts: the inference model and generative model, as follows [70].

3.2.1. Inference Model

$$q(H|X, A) = \prod_{i=1}^n \prod_{j=1}^n q(h_i|X, A), \text{ with } q(h_i|X, A) = \mathcal{N}(h_i|\mu_i, \text{diag}(\sigma_i^2)) \quad (23)$$

where $\mu = \text{GCN}_\mu(X, A)$ is the matrix of mean vectors μ_i , similarly $\log \sigma = \text{GCN}_\sigma(X, A)$. The two layer spectral-based GCN is defined as $\text{GCN}(X, A) = \tilde{A} \text{ReLU}(\tilde{A} X W_0) W_1$ with the weight matrices W_i . $\text{GCN}_\mu(X, A)$ and $\text{GCN}_\sigma(X, A)$ share the first layer parameters W_0 . $\text{ReLU}(\cdot) = \max(0, \cdot)$ and $\tilde{A} = D^{-1/2} A D^{-1/2}$ is the symmetrically normalized adjacency matrix.

3.2.2. Generative Model

$$p(A|H) = \prod_{i=1}^n \prod_{j=1}^n p(A_{ij}|h_i, h_j), \text{ with } p(A_{ij} = 1|h_i, h_j) = \sigma(h_i^T h_j) \quad (24)$$

where $\sigma(\cdot)$ is the logistic sigmoid function. The VGAE optimizes the variational lower bound \mathcal{L} with respect to the parameters W_i :

$$\mathcal{L} = \mathbb{E}_{q(H|X,A)} [\log p(A|H)] - \text{KL} [q(H|X,A)||p(H)] \quad (25)$$

where $\text{KL}[q(\cdot)||p(\cdot)]$ is the Kullback-Leibler divergence between two distributions $q(\dots)$ and $p(\cdot)$ and a Gaussian prior $p(H) = \prod_i p(h_i) = \prod_i \mathcal{N}(h_i|0, I)$

As GCNs can capture the nonlinear relationship among diseases, drugs and biomarkers in biological networks, more and more GCN-based methods have been proposed for biomarker discovery.

3.2.3. Disease-Related Biomarker Discovery

Singh and Lio [71] propose a constrained VGAE variant for predicting disease-gene associations. Wang X. et al. [72] define a new cluster loss function and a dropout mechanism based on the GCN and graph embedding method to improve the generalization ability for predicting gene-disease associations. In order to analyze the underlying mechanism of cancer, Schulte-Sasse et al. [73] design GCNs for classifying and predicting cancer genes. Cai et al. [74] propose a GCN based on fine-grained edge dropout and coarse-grained node dropout to reduce the over-fitting in sparse graphs for predicting synthetic lethality in human cancers. Chereda et al. [75] combine the PPI network and gene expression data for patients and utilize GCN to classify the vertices in the patient's sub-network for predicting breast cancer metastasis. Rhee et al. [76] propose a hybrid approach of relation networks and localized graph convolutional filtering for breast cancer subtype classification.

Pan and Shen [77] propose a semi-supervised multi-label graph convolution model (DimiG), which does not rely on known association information between miRNAs and diseases to indirectly predict the association between miRNAs and diseases. Li J. et al. [78] design a GCN to learn the feature representations of miRNAs and diseases from the miRNA functional similarity network and disease semantic similarity network, respectively, to predict all miRNAs related to breast cancer without any known related miRNAs. Li C. et al. [79] integrate miRNA disease, miRNA gene, disease-gene, and PPI networks to extract the features for predicting miRNA disease associations. Using the FastGCN algorithm and the Forest by Penalizing Attributes (Forest PA) classifier, Wang L. et al. [80] can accurately predict potential circRNA disease associations. Wu et al. [81] propose a graph autoencoder to learn the feature representation of lncRNAs and diseases from the bipartite graph associated with lncRNA disease, and the score of the lncRNA disease interaction was calculated from the inner product of the two potential factor vectors. Ding et al. [82] use VGAE to learn the features of miRNAs and diseases from the heterogeneous networks consisting of miRNA similarity network, disease similarity network and known miRNA disease association network for predicting potential miRNA disease associations. In the prediction of disease-related RNAs with limited known data, the integration of multi-view information can help us understand complex biological networks more comprehensively. Ding et al. [83] further design a multi-view VGAE, combined with matrix factorization to predict potential miRNA-disease associations. In addition, the Laplacian matrices are incorporated with a deep factorization machine to predict miRNA-disease associations [84].

3.2.4. Drug-Related Biomarker Discovery

When a drug is taken with another drug, the expected efficacy of drugs may be significantly changed. Therefore, research on drug-drug interaction (DDI) is essential to reduce the occurrence of adverse drug events and maximize the synergistic benefits in the treatment of diseases. Zitnik et al. [93] predict the side effects between drugs from a multi-modal heterogeneous network consisting of PPI, drug-protein targets, and drug-drug interactions, where each side effect is represented by a different edge. Ma et al. [94] propose a framework of a multi-view drug graph encoder based on the attention mechanism, which is used to measure the drug similarity. Wang F. et al. [95] propose a GCN with multiple graph kernels for predicting drug-drug interactions.

The accurate structure prediction can fully clarify the biological mechanism of protein action on a molecular scale, and its application in drug development is of great significance. However, Compared to CNN-based methods, GCN-based methods have shown more powerful capabilities in learning the effective structure of proteins from simplified graphical representations [85]. Zamora-Resendiz and Crivelli [86] propose a spatial GCN for learning protein structures with the natural spatial representation of molecular structures. Gligorijevic et al. [87] model the protein structure as a graph to predict the protein function based on GCNs. Feng et al. [88] introduce a GCN into drug target identification by learning the molecular structure information of drugs. Tran et al. [89] propose a GCN-based framework to learn representations of the drugs and targets for predicting drug-target interactions.

The combination of genomics data and drug information for drug response prediction has promoted the development of personalized medicine. Huang et al. [90] combine a GCN with an autoencoder to predict the association between miRNA and drug resistance. Liu Q. et al. [91] predict the therapeutic effect of drugs on cancer cells by con-

structing a cancer cell information sub-network and a drug structure sub-network. Considering the complexity of cancer factors, Singha et al. [92] integrate biological network, genomics, inhibitor analysis, and disease–gene association data into large heterogeneous networks. Multiple graph convolution blocks and attention propagation are used for predicting the effect of pharmacotherapy.

3.2.5. Image Biomarker Discovery for Brain Disorders

Before GCNs are introduced, CNN-based image analysis has been widely used in various studies, especially in brain image analysis [96–99]. Actually, image data can be represented as a graph structure appropriate for the use of GCNs. Therefore, GCNs have many applications in the field of medical imaging analysis. Parisot et al. [100] propose a framework to exploit GCN and involves representing populations as a sparse graph, where its vertices are associated with imaging-based feature vectors, while phenotypic information is integrated as edge weights and applied to study autism spectrum disorder and Alzheimer’s disease. Gopinath et al. [101] propose an approach to enable direct learning of surface data across compatible surface bases and its superiority is illustrated with applications to brain parcellation.

Ktena et al. [102] exploit concepts of graph convolutions to estimate the similarity between irregular graphs which is alter applied to study the structural or functional connections within the brain. Zhai et al. [103] construct a generative model using graph convolution and VAE to predict the abnormal areas of pulmonary artery-vein. In order to lift the restrictions of fixed graphic structure for a model, Zhang and Pierre [104] propose a spatial GCN-based learning model to classify different brain connections and predict the association between brain connection sub-networks and diseases. Yang et al. [105] integrate different modalities of medical imaging (both brain structural and functional MRIs) with GCNs for predicting bipolar disorder.

4. Other Methods

4.1. Network Energy-Based Methods

Consider a network $G = (V, E)$ with some of its vertices labelled as 1 or 0 and others unlabelled vertices. Based on Boltzmann principle and Ising model in the statistic physics, Chen et al. define the network energy with vertex labels and edges and then develop the network energy-based method for calculating the possibility of vertex v_i being labeled as 1, as follows [3].

$$c_{ne}(i) = \frac{1}{1 + \exp(-[\alpha + (\beta - 1)M_{i0} + (\gamma - \beta)M_{i1}])} \quad (26)$$

where M_{i0} and M_{i1} are the numbers of neighbors of vertex v_i with label 0 and 1, respectively, and can be calculated as

$$M_{i0} = \sum_{v_j \in V} a_{ij}(1 - x_j) \text{ and } M_{i1} = \sum_{v_j \in V} a_{ij}x_j \quad (27)$$

where $x_j \in \{0, 1\}$ is the labelled value of vertex v_j and a_{ij} is the (i, j) -entry of the adjacent matrix of the network.

Network energy-based centrality can be viewed as the extension of classical vitality measures as it quantifies the difference of the network energy between two possible labels of a network element. Different from previously introduced centrality, the network energy-based methods contain the trainable parameters α, β , and γ . In addition, as the network energy is a scalar, the energy of multiple networks can be added together. Therefore, the network energy-based methods on a single network can be straightforwardly extended to multiple networks [3, 4].

Chen et al. have applied the network energy-based methods based on both single network and multiple networks to identify disease-associated genes [3, 106–108]. Note that in Equation (26), only the information of direct neighbors of vertex v_i is used. To take the information of indirect neighbors into account, Chen et al. design a network energy-based method with a network kernel for identifying disease genes [109]. Let $w = [\alpha, \beta - 1, \gamma - \beta]^T$ be the learnable parameter vector and $x_i = [1, M_{i0}, M_{i1}]^T$ be the feature vector of vertex v_i . Then, network energy-based method (26) can be expressed as follows:

$$c_{ne}(i) = \frac{1}{1 + \exp(-w^T x_i)} \quad (28)$$

Luo et al. define the vertex feature vector different from $x_i = [1, M_{i0}, M_{i1}]^T$ and use the generalized centrality with the expression of Equation (28) to predict disease genes [110, 111]. Ding et al. use the random walk to get the features of vertices and use the expression Equation (28) to predict disease-associated circRNAs [43].

4.2. Matrix Factorization-Based Methods

As the entries of the adjacent matrix of an unweighted network are either 0 or 1, the adjacent matrices can be

viewed as nonnegative matrices. Therefore, the nonnegative matrix factorization (NMF) can be used to learn the features of network elements as inputs of machine learning methods for downstream analysis. Mathematically, given a nonnegative matrix $A \in \mathbb{R}^{n \times m}$, and a positive integer $r < \min\{n, m\}$, NMF tries to find two nonnegative matrices $U \in \mathbb{R}^{n \times r}$ and $V \in \mathbb{R}^{m \times r}$ such that

$$A \approx UV^T. \quad (29)$$

There are several ways to measure the best approximation of A by UV^T , one of which has widely been used is minimizing the Euclidean distance between A and UV^T as follows [112, 113]:

$$\begin{aligned} & \text{minimize} && \|A - UV^T\|_F^2 \\ & \text{subject to} && U \geq 0, V \geq 0 \end{aligned} \quad (30)$$

where $\|\cdot\|_F$ is the Frobenius norm of a matrix and ≥ 0 stands for "entry-wise greater or equal to zero". Each row vector of matrices U and V can be explained as the feature vector network vertices. For example, consider $A \in \mathbb{R}^{n \times m}$ to be the adjacent matrix of the associate network of n diseases and m genes. Then, the i -th row vector of matrix U is the r -dimensional feature vector of disease i while the j -th row vector of matrix V is the r -dimensional feature vector of gene j . In the literature, NMF is often used for learning the features of network elements for clustering [114–116].

A could be a symmetric matrix when it presents the adjacent matrix of interaction networks such as PPI networks [16] and (DDI) networks [17]. Then, symmetrical nonnegative matrix factorization method [117] can be used to learn the features of network elements. The optimization formulation of NMF (27) can also integrate other information about the elements of a network to learn more reasonable features. For example, let S_R be the adjacent matrix of the similarity network for elements corresponding to rows in A while S_C be the adjacent matrix of the similarity network for elements corresponding to columns in A . Then, the optimization problem can be formulated as follows:

$$\begin{aligned} & \text{minimize} && \|A - UV^T\|_F^2 + \text{tr}(U^T L_R U) + \text{tr}(V^T L_C V) \\ & \text{subject to} && U \geq 0, V \geq 0 \end{aligned} \quad (31)$$

where $\text{tr}(\cdot)$ is the trace of a matrix. L_R and L_C are the Laplace matrix of the similarity networks for elements corresponding to rows and columns, respectively.

In the early years, Pascual-Montano et al. develop a software package for NMF and applications in biology [118] while Tian et al. review the matrix decomposition methods in bioinformatics [119], which includes NMF and applications for biomarker discovery. Recently, Fujita et al. integrate NMF and pathway signature analysis for biomarker discovery [120]. Jamali et al. develop NMF methods for predicting drug-related biomarkers (microRNA) [121] and proteins [122]. Luo et al. apply NMF to predict disease-related biomarkers (genes) [123]. Lin and Ma predict disease-related biomarkers (lncRNA) in heterogeneous networks with co-regularized NMF [124]. Peng et al. develop Rnmflp for predicting disease-related biomarkers (circRNAs) based on robust NMF and label propagation [125].

NMF of adjacent matrices of networks has been extended in two different ways for biomarker discovery. Traditional NMF only involves the multiplications and additions, which is called linear factorization, and only has one hidden layer [69]. One way to extend the linear NMF is to introduce nonlinear factorization. Bayesian or logistic matrix factorization [69] is one of the widely used nonlinear NMF for biomarker discovery. Chen et al. use Bayesian NMF for predicting disease-related biomarkers (miRNA) [126]. Furthermore, Ding et al. develop a deep belief network-based matrix factorization model with multiple layers and nonlinear transformation for predicting disease-related biomarkers (miRNA) [127]. Networks with one or two types of vertices can be represented by planar graphs and their adjacent matrices are two-dimensional tensors. Networks with more than two types of vertices are represented by multi-dimensional graphs and as a result, their adjacent matrices are high-dimensional tensors. Another way to extend NMF for adjacent matrices of networks is to design the nonnegative high-dimensional tensor factorization. Jamali et al. construct a three-dimensional graph with three types of vertices: drugs, targets, and diseases, and develop a nonnegative tensor decomposition method for drug repositioning [128].

5. Discussions and Future Directions

A pair of vertices in a network, which forms an edge, could play a very important role in many biological processes, including the development of diseases [129]. The studies in [9] show that synthetic lethality between two genes can personalize targeted therapies. Most centralities for vertices can be also defined for edges, and edge centralities have been used to predict essential proteins [130]. Luo et al. [131] use the random walk (node2vec) to learn the features of disease gene association from networks for a deep learning model to predict disease-related biomarkers. However, compared to vertex centralities, edge centralities have been paid much less attention to in the existing

literature of network learning. Therefore, network learning for edges can be a promising direction for drug discovery. If genes are mapped in some proper networks, the lethality between two genes can be viewed to study the centralities of edges in such networks.

Biological networks are typically dynamics. For example, some edges appearing at one-time point (or subcellular localization) may disappear at another time point (or one subcellular localization) in PPI networks [132–134]. The traditional centrality-based methods have been applied to dynamic biological networks to learn the knowledge for biomarker discovery [135, 136]. Another promising direction for network learning is to combine dynamic biological networks with deep neural networks to learn the properties or features of network elements for drug discovery. Network biology is useful for modeling complex biological phenomena [137] and has attracted attention with the advent of novel network (especially deep) learning methods. Similar to other deep learning methods, network deep learning often suffers from the lack of interpretability. However, the interpretability of network learning models could be the top priority in the domain of biomarker discovery. The third promising direction is to increase the interpretability of network deep learning models for biomarker discovery by incorporating more biological knowledge into models.

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